# ECE 171A: Linear Control System Theory 

Discussion 5: Review on Complex numbers, rational functions, and laplace transform

Yang Zheng<br>Assistant Professor, ECE, UCSD

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## Outline

Complex numbers

Complex functions and Rational functions

Laplace transform

## Outline

# Complex numbers 

## Complex functions and Rational functions

## Laplace transform

## Complex numbers

A complex number $z \in \mathbb{C}$ has a real and an imaginary part, and can be represented in either Cartesian or Polar coordinates.

- Cartesian form: $z$ is represented as a linear combination of basis vectors in the complex plane, i.e., the sum of the real part and imaginary part.
- Polar form: $z$ is represented by a magnitude $r$ and phase $\theta$.


Figure: An illustration of the complex plane. The real part of a complex number $z=x+i y$ is $x$, and its imaginary part is $y$.

## Operations

## Cartesian <br> Polar

$$
z \quad z=a+b i, \quad a, b \in \mathbb{R} \quad z=r e^{i \theta}, r, \theta \in \mathbb{R}
$$

$\bar{z}$ Conjugate

$$
\bar{z}=a-b i
$$

$$
\bar{z}=r e^{-i \theta}, r, \theta \in \mathbb{R}
$$

Conversion $\quad a=r \cos \theta, b=r \sin \theta \quad r=\sqrt{a^{2}+b^{2}}, \theta=\arctan \left(\frac{b}{a}\right)$

$$
\begin{array}{llrl}
\operatorname{Re}(z) & a & =\frac{1}{2}(z+\bar{z}) & r \cos \theta
\end{array}=\frac{r}{2}\left(e^{i \theta}+e^{-i \theta}\right)
$$

- In this course, we typically express the frequency variable $s$ as a complex number $s=\sigma+i \omega$ :


## Euler's Formula

## Definition

For any real number $t$, we define $e^{i t}=\cos t+i \sin t$


Figure: Euler's definition of $e^{i \theta}$.

Euler's formula: A famous example is $e^{\pi i}=\cos \pi+i \sin \pi=-1$, leading to

$$
e^{\pi i}+1=0
$$

This combines the five most basic quantities in mathematics $e, \pi, i, 1$ and 0 .

## Computation

- Addition and subtraction in Cartesian form tend to be simpler:

$$
\begin{aligned}
z_{1} & =a+b i, \quad z_{2}=c+d i \\
\Rightarrow \quad z_{1}+z_{2} & =a+c+(b+d) i \\
\Rightarrow \quad z_{1}-z_{2} & =a-c+(b-d) i
\end{aligned}
$$

- On the other hand, multiplication and division tend to be simpler in polar form:

$$
\begin{aligned}
z_{1} & =r_{1} e^{i \theta_{1}}, \quad z_{2}=r_{2} e^{i \theta_{2}} \\
\Rightarrow \quad z_{1} z_{2} & =r_{1} r_{2} e^{i\left(\theta_{1}+\theta_{2}\right)} \\
\Rightarrow \quad \frac{z_{1}}{z_{2}} & =\frac{r_{1}}{r_{2}} e^{i\left(\theta_{1}-\theta_{2}\right)}
\end{aligned}
$$

Multiplication and division and in the complex plane correspond to

- scaling the magnitude by the original magnitudes,
- and shifting phase by the sum or difference of the original phases.


## Example

## Example

Let $z_{1}=-1+\sqrt{3} i$ and $z_{2}=\bar{z}_{1}$. Find polar forms for $z_{1}$ and $z_{2}$. Calculate $z_{1}+z_{2}, z_{1} z_{2}$, and $\frac{z_{1}}{z_{2}}$.

- In polar form, we have the magnitude is given by

$$
|z|=\sqrt{(-1)^{2}+(\sqrt{3})^{2}}=2 .
$$

- The phase is given by

$$
\theta=\arctan \left(\frac{\sqrt{3}}{-1}\right)=\frac{2 \pi}{3}
$$

- Then, we have

$$
z_{1}=2 e^{\frac{2 \pi}{3} i}, \quad z_{2}=2 e^{\frac{-2 \pi}{3} i} .
$$

- In the Cartesian form, we have

$$
z_{2}=\bar{z}_{1}=-1-\sqrt{3} i, \quad z_{1}+z_{2}=-2, \quad z_{1}-z_{2}=2 \sqrt{3} i .
$$

## Example

- In the Cartesian form, we have

$$
\begin{aligned}
& z_{1} z_{2}=(-1+\sqrt{3} i)(-1-\sqrt{3} i)=1-\sqrt{3} i+\sqrt{3} i-3 i^{2}=4 \\
& \frac{z_{1}}{z_{2}}=\frac{-1+\sqrt{3} i}{-1-\sqrt{3} i} \cdot \frac{-1+\sqrt{3} i}{-1+\sqrt{3} i}=\frac{1-2 \sqrt{3} i+3 i^{2}}{4}=\frac{-1-\sqrt{3} i}{2}
\end{aligned}
$$

- In the polar form, we have

$$
\begin{aligned}
z_{2} & =\bar{z}_{1}=2 e^{\frac{-2 \pi}{3} i} \\
z_{1}+z_{2} & =2\left(e^{\frac{2 \pi}{3} i}+e^{\frac{-2 \pi}{3} i}\right)=2\left(2 \cos \left(\frac{2 \pi}{3}\right)\right)=-2 \\
z_{1}-z_{2} & =2\left(e^{\frac{2 \pi}{3} i}-e^{\frac{-2 \pi}{3} i}\right)=2\left(2 \sin \left(\frac{2 \pi}{3}\right)\right) i=2 \sqrt{3} i
\end{aligned}
$$

and

$$
\begin{aligned}
z_{1} \cdot z_{2} & =2 e^{\frac{2 \pi}{3} i} \cdot 2 e^{\frac{-2 \pi}{3} i}=4 e^{\left(\frac{2 \pi}{3} i-\frac{2 \pi}{3} i\right)}=4 \\
\frac{z_{1}}{z_{2}} & =\frac{2 e^{\frac{2 \pi}{3} i}}{2 e^{\frac{-2 \pi}{3} i}}=e^{\frac{4 \pi}{3} i}
\end{aligned}
$$

## Outline

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Complex functions and Rational functions

## Laplace transform

## Complex functions

A complex valued function ${ }^{1}$ on some interval $I=(a, b) \subseteq \mathbb{R}$ is $f: I \rightarrow \mathbb{C}$.

- Such a function can be written as in terms of its real and imaginary parts,

$$
f(t)=u(t)+i v(t)
$$

in which $u, v: I \rightarrow \mathbb{R}$ are two real valued functions.

A complex valued function of a complex variable is a function $f(z): \mathbb{C} \rightarrow \mathbb{C}$.

- If $z=x+i y$, then $f(z)$ corresponds to a function

$$
F(x, y)=u(x, y)+i v(x, y)
$$

of the two real variables $x$ and $y$.

- We can consider $f(z)$ is a function from $\mathbb{R}^{2}$ to $\mathbb{R}^{2}$.

[^0]
## Example

## Example

1. $f(z)=z$ corresponds to $F(x, y)=x+i y \quad(u=x, v=y)$;
2. $f(z)=\bar{z}$ corresponds to $F(x, y)=x-i y \quad(u=x, v=-y)$;
3. $f(z)=\operatorname{Re}(z)$ corresponds to $F(x, y)=x \quad(u=x, v=0)$;
4. $f(z)=|z|$ corresponds to $F(x, y)=\sqrt{x^{2}+y^{2}} \quad\left(u=\sqrt{x^{2}+y^{2}}, v=0\right)$;
5. $f(z)=z^{2}$ corresponds to $F(x, y)=\left(x^{2}-y^{2}\right)+i(2 x y)$ $\left(u=x^{2}-y^{2}, v=2 x y\right) ;$
6. $f(z)=e^{z}$ corresponds to $F(x, y)=e^{x} \cos y+i\left(e^{x} \sin y\right)$ $\left(u=e^{x} \cos y, v=e^{x} \sin y\right) ;$
7. $f(z)=\frac{1}{z}$ corresponds to $F(x, y)=\frac{x}{x^{2}+y^{2}}+i \frac{-y}{x^{2}+y^{2}}$

$$
\left(u=\frac{x}{x^{2}+y^{2}}, v=\frac{-y}{x^{2}+y^{2}}\right) ;
$$

## Polynomials

A polynomial of a complex variable $z=x+i y$ is a function of the form

$$
P(z)=a_{n} z^{n}+a_{n-1} z^{n-1}+\ldots+a_{0}
$$

where $a_{i}, i=0,1, \ldots, n$ are complex numbers.

- We focus on polynomials with real coefficient ( $a_{i} \in \mathbb{R}, i=1, \ldots, n$ ).
- The real and imaginary parts of a polynomial $P(z)$ are polynomials in $x, y$ :

$$
\begin{aligned}
& P_{1}(z)=z^{2}=\left(x^{2}-y^{2}\right)+i(2 x y) \\
& P_{2}(z)=(1+i) z^{2}-3 i z=\left(x^{2}-y^{2}-2 x y+3 y\right)+\left(x^{2}-y^{2}+2 x y-3 x\right) i .
\end{aligned}
$$

- In the polar form $z=r e^{i \theta}$, we have

$$
z^{n}=r^{n} e^{i n \theta}, \quad(\bar{z})^{n}=r^{n} e^{-i n \theta}
$$

- Thus, we have $\overline{\left(z^{n}\right)}=(\bar{z})^{n}$.
- In general, for any polynomial $p(z)$ with real coefficients, we have

$$
\overline{p(z)}=p(\bar{z}), \quad \overline{p(i \omega)}=p(-i \omega)
$$

## Fundamental Theorem of Algebra

Fundamental Theorem of Algebra (first proved by Gauss in 1799): if $P(z)$ is a non-constant polynomial, then $P(z)$ has a complex root. In other words, there exists a complex number $c$ such that $P(c)=0$.

- If $P(z)$ is a polynomial of degree $n>0$, then $P(z)$ can be factorized into linear factors:

$$
P(z)=a\left(z-\lambda_{1}\right) \cdots\left(z-\lambda_{n}\right),
$$

for complex numbers $a$ and $\lambda_{1}, \ldots, \lambda_{n}$.

Every non-constant polynomial $P(z)$ with real coefficients can be factorized into (real) polynomials of degree one or two.

- In other words, the roots of polynomial $P(z)$ with real coefficients come with pairs $\lambda_{i}=x+y i$ and $\lambda_{i+1}=x-y i$.


## Rational functions

A rational function $G(z)$ is a quotient of two polynomials

$$
G(z)=\frac{P(z)}{Q(z)}
$$

where $P(z)$ and $Q(z)$ are polynomials and $Q(z)$ is not identically zero.

## Example

Here are some examples

$$
\begin{aligned}
G_{1}(z) & =\frac{1}{z} \\
G_{2}(z) & =\frac{1}{z+1} \\
G_{3}(z) & =\frac{z+1}{z^{2}+z+1}
\end{aligned}
$$

## Outline

Complex numbers<br>\section*{Complex functions and Rational functions}

Laplace transform

## Laplace transform

## Definition

The Laplace transform of a function $f(t)$ is defined by the integral

$$
F(s)=\mathcal{L}(f(t))=\int_{0}^{\infty} e^{-s t} f(t) d t
$$

for those complex variable $s$ where the integral converges.

The Laplace transform ${ }^{2}$ takes a function of time and transforms it to a function of a complex variable $s$.

- Because the transform is invertible, no information is lost
- It is reasonable to think of a function $f(t)$ and its Laplace transform $F(s)$ as two views of the same phenomenon.
- Each view has its uses and some features of the phenomenon are easier to understand in one view or the other.

[^1]
## Example 1

## Example

Calculate the Laplace transform of the step function

$$
f(t)= \begin{cases}0 & t<0 \\ 1 & t \geq 0\end{cases}
$$

Give the region in the complex s-plane where the integral converges. We have

$$
\begin{aligned}
F(s)=\mathcal{L}(f(t)) & =\int_{0}^{\infty} e^{-s t} f(t) d t \\
& =\int_{0}^{\infty} e^{-s t} d t \\
& =\left.\frac{e^{-s t}}{-s}\right|_{0} ^{\infty} \\
& =\frac{1}{s}
\end{aligned}
$$

if $\operatorname{Re}(s)>0$, otherwise it is undefined.

## Example 2

## Example

Calculate the Laplace transform of the shifted delta function

$$
\delta(t-a)=\left\{\begin{array}{ll}
\infty & t=a \\
0 & \text { otherwise }
\end{array}, \quad \int_{-\infty}^{\infty} \delta(t-a) d t=1 .\right.
$$

By definition, we have

$$
\begin{aligned}
F(s)=\mathcal{L}(f(t)) & =\int_{0}^{\infty} e^{-s t} \delta(t-a) d t \\
& =\int_{0}^{\infty} e^{-s a} \delta(t-a) d t \\
& =e^{-s a} \int_{0}^{\infty} \delta(t-a) d t \\
& =e^{-s a}
\end{aligned}
$$

In particular, when $a=0$, we have

$$
F(s)=\mathcal{L}(f(t))=\int_{0}^{\infty} e^{-s t} \delta(t) d t=1
$$

## Example 3

## Example

Calculate the Laplace transform of the exponential function

$$
f(t)=e^{a t}
$$

- Given the region in the complex $s$-plane where the integral converges.
- We have

$$
\begin{aligned}
F(s)=\mathcal{L}(f(t)) & =\int_{0}^{\infty} e^{-s t} e^{a t} d t \\
& =\int_{0}^{\infty} e^{(a-s) t} d t \\
& =\left.\frac{e^{(a-s) t}}{a-s}\right|_{0} ^{\infty} \\
& =\frac{1}{s-a}
\end{aligned}
$$

if $\operatorname{Re}(s)>\operatorname{Re}(a)$, otherwise, it is undefined.

## Example 4

## Example

Compute the Laplace transform of the cosine function

$$
f(t)=\cos (\omega t)
$$

- We use the formula

$$
\cos (\omega t)=\frac{e^{i \omega t}+e^{-i \omega t}}{2}
$$

- So we have

$$
\begin{aligned}
F(s)=\mathcal{L}(f(t)) & =\int_{0}^{\infty} e^{-s t}\left(\frac{e^{i \omega t}+e^{-i \omega t}}{2}\right) d t \\
& =\frac{1}{2}\left(\frac{1}{s-i \omega}+\frac{1}{s+i \omega}\right) \\
& =\frac{s}{s^{2}+\omega^{2}}
\end{aligned}
$$


[^0]:    ${ }^{1}$ See https://www.math. columbia.edu/~rf/complex2.pdf.

[^1]:    ${ }^{2}$ See https://math.mit.edu/~jorloff/18.04/notes/topic12.pdf.

