Block Factor-width-two Matrices and Their Applications to Semidefinite and Sum-of-squares Optimization

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Outline

Introduction: inner/outer approximations for SDPs

A new class of block factor-width-two matrices

Applications to SDPs and SOS optimization

Conclusions



Introduction

A primal standard SDP is in the form of

$$\begin{split} p^{\star} &= \min_{X} \quad \langle C, X \rangle \\ \text{subject to} \quad \langle A_i, X \rangle &= b_i, i = 1, \dots, m, \\ \quad X \in \mathbb{S}^n_+. \end{split}$$

SDPs are more powerful than LP or SOCP

 Applications: control theory, polynomial optimization, machine learning, power grid, robotics, etc.





Introduction: inner/outer approximations for SDPs

Introduction

A primal standard SDP is in the form of

$$\begin{split} p^{\star} &= \min_{X} \quad \langle C, X \rangle \\ \text{subject to} \quad \langle A_i, X \rangle &= b_i, i = 1, \dots, m, \\ \quad X \in \mathbb{S}^n_+. \end{split}$$

However, SDPs are much more expensive to solve than LP or SOCP

- ▶ Standard interior-point methods scale as $O(mn^3 + m^2n^2)$ per iteration
- LPs with millions of variables and constraints can be solved reliably.
- General-purpose solvers cannot efficiently handle large SDP problems $(n \approx 1000, \text{ and } m: \text{ a few thousands})$
- Exploiting sparsity and structures for improving efficiency is an active research topic^{1,2}.

¹Zheng, Fantuzzi, and Papachristodoulou. "Chordal and factor-width decompositions for scalable semidefinite and polynomial optimization." Annual Reviews in Control 52 (2021): 243-279.

²Majumdar, Hall, and Ahmadi. "Recent scalability improvements for semidefinite programming with applications in machine learning, control, and robotics." Annual Review of Control, Robotics, and Autonomous Systems 3 (2020): 331-360.

Something simpler: inner/outer approximations

Inner approximations

▶ Suppose we have a simpler cone $\mathcal{K} \subset \mathbb{S}_+^n$. Solving an instance of

$$\begin{split} \min_{X} & \langle C, X \rangle \\ \text{subject to} & \langle A_i, X \rangle = b_i, i = 1, \dots, m, \\ & X \in \mathcal{K} \subset \mathbb{S}^n_+. \end{split}$$

gives us an upper bound on p^{\star} .

Outer approximations

Suppose we have a simpler cone $\mathbb{S}^n_+ \subset \hat{\mathcal{K}}$. Solving an instance of

$$\begin{array}{ll} \min_{X} & \langle C, X \rangle \\ \text{subject to} & \langle A_i, X \rangle = b_i, i = 1, \ldots, m, \\ & X \in \hat{\mathcal{K}}. \end{array}$$

gives us a lower bound on p^{\star} .



Introduction: inner/outer approximations for SDPs

Which cones to use?

Ahmadi and Majumdar³ considered the cones of *diagonally dominant* and *scaled diagonally dominant* matrices

• A symmetric matrix $A \in \mathbb{S}^n$ is diagonally dominant if

$$a_{ii} \ge \sum_{j \ne i} |a_{ij}|, \qquad i = 1, \dots, n.$$

A symmetric matrix $A \in \mathbb{S}^n$ is scaled-diagonally dominant if there exists a diagonal matrix D with nonnegative entries, such that

DAD $\,$ is diagonally dominant

We denote

 $\mathcal{DD}_n = \{ X \in \mathbb{S}^n \mid X \text{ is diagonally dominant} \} \subset \mathbb{S}^n_+$ $\mathcal{SDD}_n = \{ X \in \mathbb{S}^n \mid X \text{ is scaled diagonally dominant} \} \subset \mathbb{S}^n_+$

• Linear optimization over \mathcal{DD}_n is an LP;

Linear optimization over SDD_n is an SOCP;

³Ahmadi, and Majumdar. "DSOS and SDSOS optimization: more tractable alternatives to sum of squares and semidefinite optimization." SIAM J. Appl. Algebra Geom 3.2 (2019): 193-230. <u>UCSanDiego</u> <u>Most source tractable alternatives to introduction: inner/outer approximations for SDPs</u>

Approximation and Conservativeness

$$\min_{X} \quad \langle C, X \rangle$$
subject to $\langle A_i, X \rangle = b_i, i = 1, \dots, m,$
 $X \in \mathcal{SDD}_n \quad (\text{or } \mathcal{DD}_n).$

First: the resulting upper bound might be very conservative.



Figure: Boundary of (x, y) such that $I_6 + xA + xB$ is PSD, SDD, or DD.

Second: using SDD_n requires a number of O(n²) small SOCP constraints, which might be an issue for large n.

UC San Diego JACOBS SCHOOL OF ENGINEERING Introduction: inner/outer approximations for SDPs

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Factor-width-two matrices

Lemma

 SDD_n is equivalent to the cone of factor-width-two matrices (Boman, Erik G., et al. 2005)

$$\mathcal{SDD}_n = \left\{ \sum_{i \in I} x_i x_i^\mathsf{T} \mid x_i \in \mathbb{R}^n, \mathsf{supp}(x_i) \le 2 \right\}$$

• Denote the cone of $n \times n$ factor-width-two matrices as \mathcal{FW}_2^n :

$$\mathcal{SDD}_n = \mathcal{FW}_2^n.$$

• Another interpretation: $P \in \mathcal{FW}_2^n$ if and only if there exists $X_{ij} \in \mathbb{S}^2_+$ s.t.

$$P = \sum_{1 \le i < j \le n} E_{ij}^{\mathsf{T}} X_{ij} E_{ij},$$

where $E_{ij} = \begin{bmatrix} E_i \\ E_j \end{bmatrix} \in \mathbb{R}^{2 \times n}, i \neq j$, and E_i is a row basis vector with 1 at the *i*-th entry.

$$E_i = \begin{bmatrix} 0 & \dots & 1 & \dots & 0 \end{bmatrix} \in \mathbb{R}^{1 \times n}$$

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Block factor-width-two matrices

A linear optimization problem over the FW_2^n cone can be written as an ${\rm SDP}$ over the cone product





Figure: Illustration of (block) factor-width-two decomposition

- For $A \in SDD_n$ or FW_2^n , each black square represents a scalar $a_{ij} \in \mathbb{R}$.
- Key idea block extension: how about each black square represents a submatrix?

$$A_{ij} \in \mathbb{R}^{k_i \times k_j}$$

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Block-partitioned matrices

Given a matrix $A \in \mathbb{R}^{n \times n}$, we say a set of integers $\alpha = \{k_1, k_2, \ldots, k_p\}$ with $k_i \in \mathbb{N}$ $(i = 1, \ldots, p)$ is a partition of A if $\sum_{i=1}^{p} k_i = n$, and A is partitioned as

$$\begin{bmatrix} A_{11} & A_{12} & \dots & A_{1p} \\ A_{21} & A_{22} & \dots & A_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ A_{p1} & A_{p2} & \dots & A_{pp} \end{bmatrix}$$

with $A_{ij} \in \mathbb{R}^{k_i \times k_j}, \forall i, j = 1, \dots, p.$



Figure: Different partitions for a 6×6 matrix: (a) $\alpha = \{1, 1, 1, 1, 1, 1\}$, (b) $\beta = \{2, 2, 2\}$, (c) $\gamma = \{4, 2\}$. From right to left, we get coarser partitions, *i.e.* $\alpha \sqsubseteq \beta \sqsubseteq \gamma$.

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Block factor-width-two matrices

Definition

A symmetric matrix $Z \in \mathbb{S}^n$ with partition $\alpha = \{k_1, k_2, \dots, k_p\}$ belongs to the class of block factor-width-two matrices, denoted as $\mathcal{FW}^n_{\alpha,2}$, if and only if

$$Z = \sum_{1 \le i < j \le p} (E_{ij}^{\alpha})^{\mathsf{T}} X_{ij} E_{ij}^{\alpha}$$
(1)

for some $X_{ij} \in \mathbb{S}^{k_i+k_j}_+$ and with $E_{ij}^{\alpha} \in \mathbb{R}^{(k_i+k_j) \times n}$ being an index matrix.



Figure: Illustration of block factor-width-two decomposition (1). The (i, j) black square represents a submatrix of dimension $k_i \times k_j$, i, j = 1, 2, 3.



A hierarchy of inner approximations

A finer partition (or subpartition) of $\alpha = \{k_1, k_2, \ldots, k_p\}$ is a partition that breaks some blocks of α into smaller blocks.

▶ Let $\alpha = \{1, 1, 1, 1, 1, 1\}$, $\beta = \{2, 2, 2\}$ and $\gamma = \{4, 2\}$. Denote $\alpha \sqsubseteq \beta \sqsubseteq \gamma$.

Theorem

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Let $\alpha \sqsubseteq \beta \sqsubseteq \gamma$ be partitions of n with $\gamma = \{\gamma_1, \gamma_2\}$, and let $\mathbf{1} = \{1, \dots, 1\}$ denote the uniform unit partition. Then,

$$\mathcal{SDD}_n=\mathcal{FW}_{1,2}^n\subseteq\mathcal{FW}_{lpha,2}^n\subseteq\mathcal{FW}_{eta,2}^n\subseteq\mathcal{FW}_{\gamma,2}^n\equiv\mathbb{S}_+^n$$

This flexibility of $\mathcal{FW}_{\alpha,2}^n$ improves the two drawbacks of \mathcal{SDD}_n . As the number p in a partition α decreases:

► First – the approximation quality improves: the largest distance between a unit-norm matrix in \mathbb{S}^n_+ and the cone $\mathcal{FW}^n_{\alpha,2}$ satisfies

$$\operatorname{dist}(\mathbb{S}^n_+,\mathcal{FW}^n_{\alpha,2}) \leq \frac{p-2}{p}$$

Second – the number of blocks in the summation decreases $\binom{p}{2}$ vs. $\binom{n}{2}$

Example

Consider the 5×5 matrix

$$P(x,y) = \begin{bmatrix} 1+6x+4y & 3x+y & 2x+y & x+4y & 3x+3y \\ 3x+y & 1+6y & 5x+3y & y & 2x+2y \\ 2x+y & 5x+3y & 1+2x+2y & x+2y & 5x+6y \\ x+4y & y & x+2y & 1+2x & 3x+3y \\ 3x+3y & 2x+2y & 5x+6y & 3x+3y & 1+6x+2y \end{bmatrix}$$

and partitions $\mathbf{1} = \{1, 1, 1, 1, 1\}$, $\alpha = \{2, 1, 1, 1\}$, $\beta = \{2, 1, 2\}$ and $\gamma = \{2, 3\}$.



Figure: Regions of the (x, y) plane for which P(x, y) belongs to the block factor-width-two cones $\mathcal{SDD}_5 \equiv \mathcal{FW}_{1,2}^5 \subseteq \mathcal{FW}_{\alpha,2}^5 \subseteq \mathcal{FW}_{\beta,2}^5 \subseteq \mathcal{FW}_{\gamma,2}^5 \equiv \mathbb{S}_+^5$

The inclusions of the plotted regions reflect the inclusions of the cones and the order relation 1 ⊑ α ⊑ β ⊑ γ.

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Applications to SDPs

- ▶ The cones $\mathcal{FW}_{\alpha,2}^n$ and its dual $(\mathcal{FW}_{\alpha,2}^n)^*$ approximate the positive semidefinite cone \mathbb{S}_+^n from the inside and from the outside
- The approximation improves as the partition α is coarsened.
- \blacktriangleright This leads to convergent sequences of upper and lower bounds on the optimal value p^{\ast}

Inner approximations

Outer approximations

$$\begin{split} U_{\alpha} &:= \min_{X} \quad \langle C, X \rangle & L_{\alpha} &:= \min_{X} \quad \langle C, X \rangle \\ \text{subject to} \quad \langle A_{i}, X \rangle &= b_{i}, \ i = 1, \dots, m, \quad \text{subject to} \quad \langle A_{i}, X \rangle &= b_{i}, \ i = 1, \dots, m, \\ \quad X \in \mathcal{FW}_{\alpha,2}^{n} & X \in (\mathcal{FW}_{\alpha,2}^{n})^{*} \end{split}$$

Corollary

Let $\alpha_1 \sqsubseteq \alpha_2 \sqsubseteq \ldots \sqsubseteq \alpha_k = \{\alpha_{k1}, \alpha_{k2}\}$ be a sequence of partitions of n. Then,

$$L_{\alpha_1} \leq \cdots \leq L_{\alpha_k} = p^* = U_{\alpha_k} \leq \cdots \leq U_{\alpha_1}.$$

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Applications to SOS optimization

Sum-of-squares (SOS) polynomials: p(x) can be represented as

$$p(x) = \sum_{i=1}^{m} f_i^2(x),$$

SDP characterization (Parrilo, Lasserre *etc.*): p(x) is SOS if and only if

$$p(x) = v_d(x)^T Q v_d(x), \qquad Q \succeq 0$$

where $v_d(x)$ is the standard monomial basis.

- ▶ **SOS:** $p(x) = v_d(x)^T Q v_d(x) : Q$ is PSD \longrightarrow SDP
- ▶ SDSOS: $p(x) = v_d(x)^T Q v_d(x) : Q$ is sdd \longrightarrow SOCP
- **DSOS:** $p(x) = v_d(x)^T Q v_d(x) : Q$ is dd \longrightarrow LP
- ▶ α -SDSOS: $p(x) = v_d(x)^T Q v_d(x) : Q$ is $\mathcal{FW}_{\alpha,2}^N \longrightarrow$ SDP with small blocks



Numerical examples

Consider a scalar polynomial optimization problem:

$$\label{eq:subjective} \begin{split} \min_{\gamma} & \gamma \\ \text{subject to} & p(x) + \gamma \geq 0, \ \forall x \in \mathbb{R}^n, \end{split}$$

Table: Computational results using SOS and $\alpha\mbox{-}{\rm SDSOS}$ relaxations.

n	Full	Number of blocks p in partition α								
	SDP	4	10	20	50					
Computational time (seconds)										
15	27.3	23.3	15.6	10.1	5.36					
20	489	252	98.1	66.8	28.1					
25	∞	1970	783	571	132					
30	∞	∞	5680	3710	840					
Objective values γ										
15	-0.92	-0.75	80.1	459	2240					
20	-0.87	-0.87	-0.11	251	1910					
25	∞	-1.07	-0.21	231	1360					
30	∞	∞	-0.37	177	1770					



Numerical results

Consider a matrix SOS program

$$\label{eq:subjection} \begin{split} \min_{\gamma} & \gamma \\ \text{subject to} & P(x) + \gamma I \succeq 0, \ \forall x \in \mathbb{R}^3, \end{split}$$

where P(x) is an $r \times r$ polynomial matrix with each element being a quartic polynomial in three variables.

r	25	30	35	40	45	50			
Computational time (seconds)									
SOS	14.4	35.9	87.2	175.0	316.0	487.8			
$\alpha ext{-}SDSOS$	10.8	16.6	25.3	36.0	57.4	71.4			
SDSOS	1.1	1.3	1.6	2.1	2.6	3.3			
Objective value γ									
SOS	266.5	316.2	460.8	562.0	746.9	919.8			
$\alpha ext{-}SDSOS$	266.5	316.2	460.8	562.0	746.9	919.8			
SDSOS	270.3	324.8	477.7	570.9	762.2	961.7			

Table: Computational results using SOS, α -SDSOS and SDSOS relaxations.



An iterative scheme

- Ahmadi and Hall⁴ introduced an iterative method over SDD_n and DD_n .
- This iterative scheme can be naturally extended to the class of block factor-width-two matrices.



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⁴Ahmadi and Hall. "Sum of squares basis pursuit with linear and second order cone programming." Algebraic and geometric methods in discrete mathematics 2017: 27-53. <u>Applications to SDPs and SOS optimization</u>

An iterative scheme



Figure: Inner/Outer approximations of the SDP (2) using \mathcal{DD}_n , \mathcal{SDD}_n , and $\mathcal{FW}_{2,\alpha}^n$ with $\alpha = \{2, \ldots, 2\}^5$.

⁵Liao, Feng-Yi, and Yang Zheng. "Iterative Inner/outer Approximations for Scalable Semidefinite Programs using Block Factor-width-two Matrices." arXiv preprint arXiv:2204.06759 (2022).

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Summary

A new class of block factor-width-two matrices



Figure: Illustration of (block) factor-width-two decomposition

It offers a new hierarchy of inner/outer approximations of PSD matrices

$$\mathcal{SDD}_n = \mathcal{FW}_{1,2}^n \subseteq \mathcal{FW}_{\alpha,2}^n \subseteq \mathcal{FW}_{\beta,2}^n \subseteq \mathcal{FW}_{\gamma,2}^n \equiv \mathbb{S}_+^n$$

Applications to inner/outer approximations of SDPs and SOS optimization

Future work

Develop special algorithms (such as non-symmetric IPM, non-smooth optimization algorithms) for problems with factor-width-two matrices.



Conclusions

Thank you for your attention!

Q & A

- Yang Zheng, Aivar Sootla, and Antonis Papachristodoulou. "Block factor-width-two matrices and their applications to semidefinite and sum-of-squares optimization." IEEE Transactions on Automatic Control (2022).
- Feng-Yi Liao, and Yang Zheng. "Iterative Inner/outer Approximations for Scalable Semidefinite Programs using Block Factor-width-two Matrices." arXiv preprint arXiv:2204.06759 (2022).