

Benign Nonconvex Landscapes in Optimal and Robust Control

Yang Zheng

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ECE Department, UC San Diego

2025 NSF Workshop on Reinforcement Learning

Jan 23, 2025

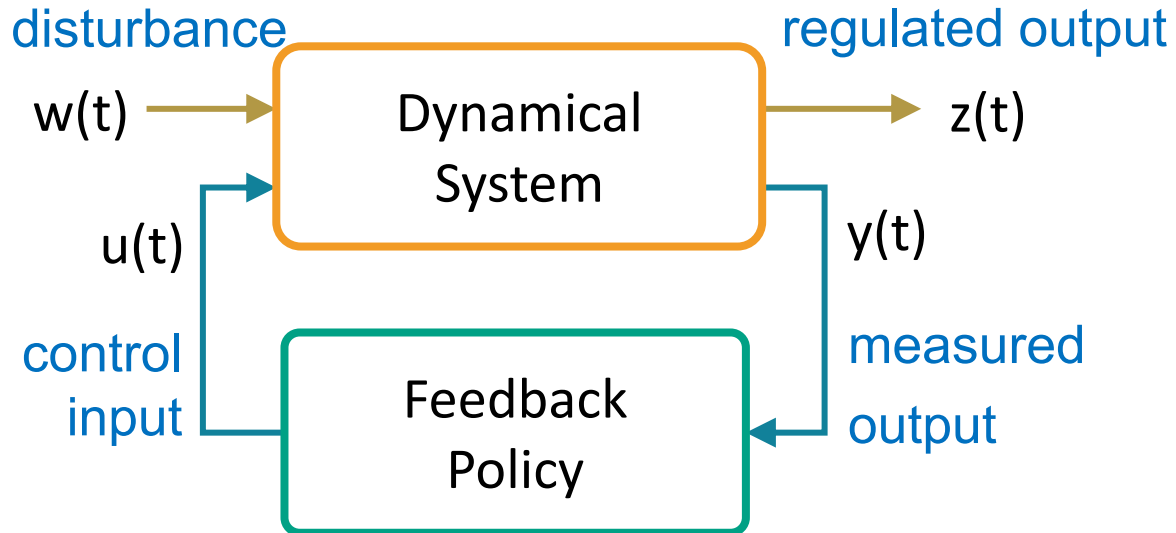
UC San Diego
JACOBS SCHOOL OF ENGINEERING
Electrical and Computer Engineering

Scalable Optimization
and Control (SOC) Lab

<https://zhengy09.github.io/soclab.html>

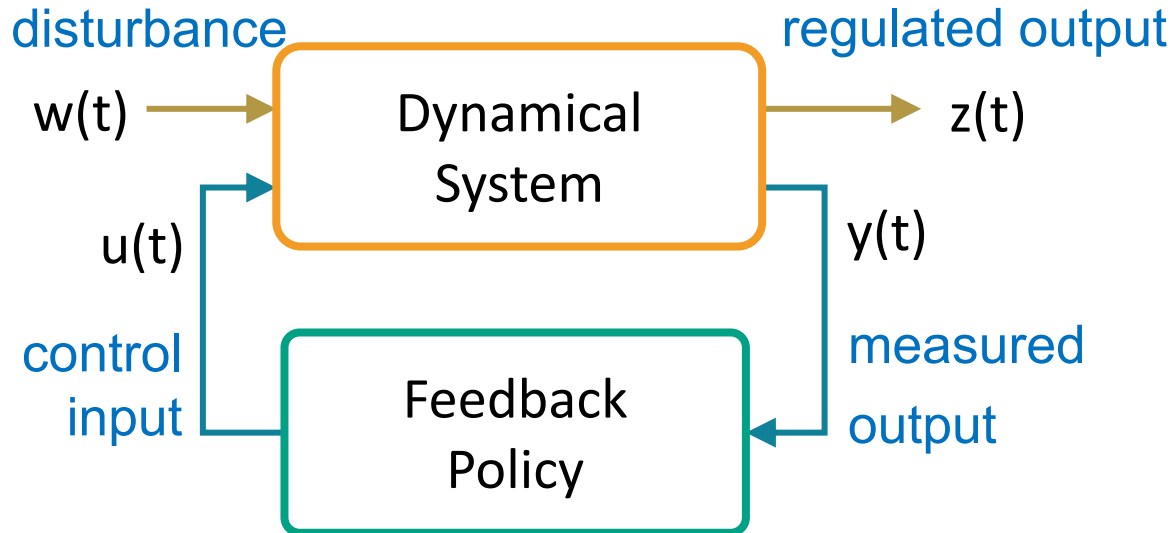
Policy Optimization in Control

□ Optimal and Robust Control

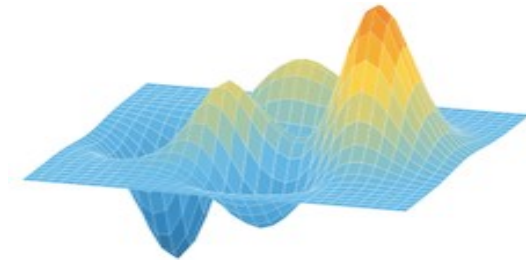


Policy Optimization in Control

□ Optimal and Robust Control



Policy
parametrization



$$\begin{aligned} \min_{\mathbf{K}} \quad & J(\mathbf{K}) \\ \text{s.t.} \quad & \mathbf{K} \in \mathcal{C} \end{aligned}$$

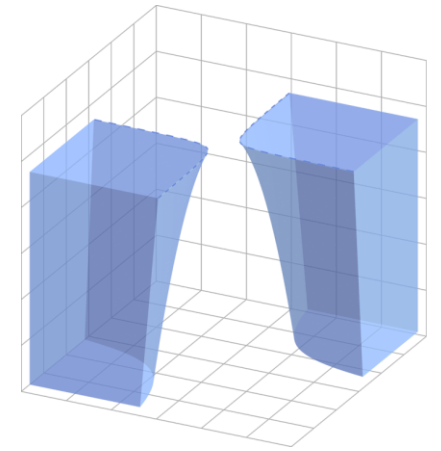
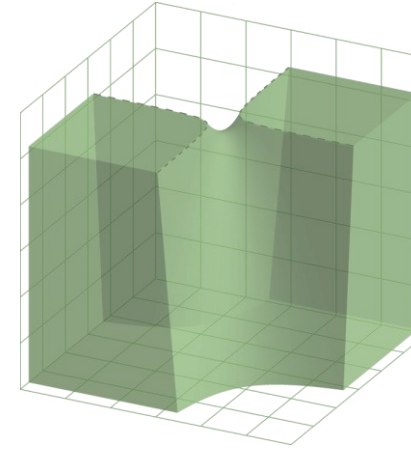
*Non-convex
Optimization
problem*

Rich Geometry in Policy Optimization

Policy
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- The set of (dynamic) stabilizing policies is **nonconvex** and even might be **not connected**. [Tang, Zheng, Li, 2023]

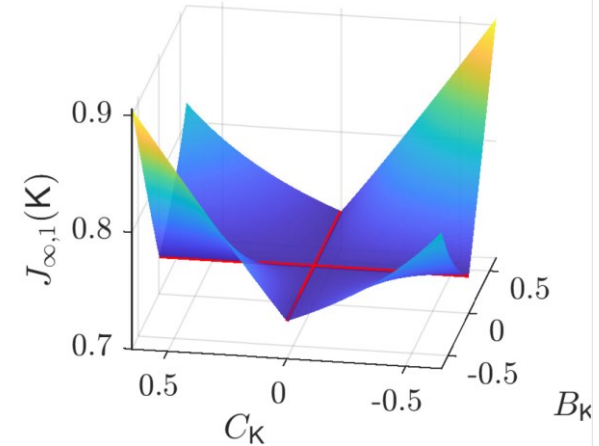
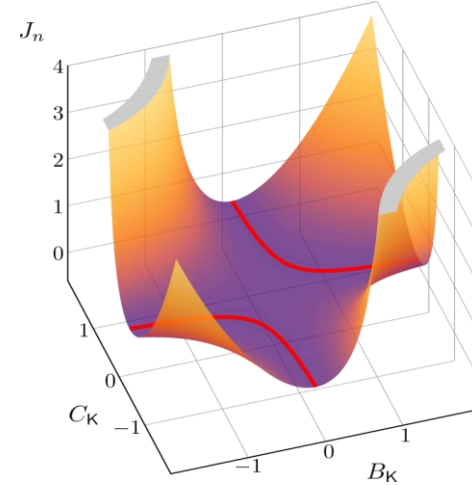
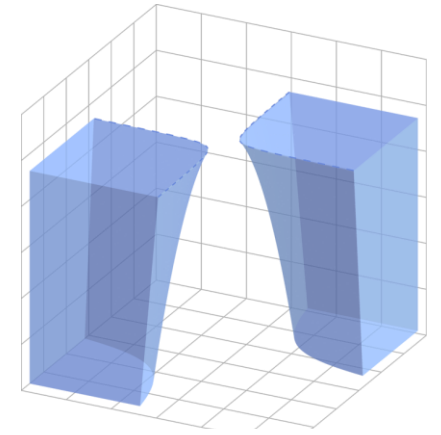
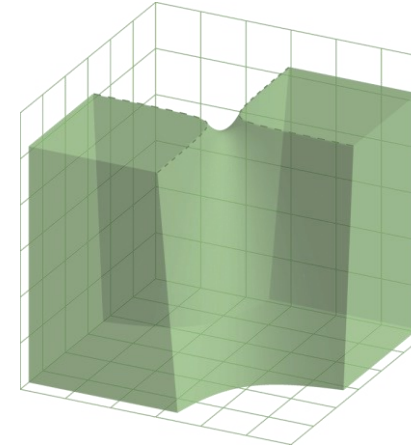
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- ❑ The set of (dynamic) stabilizing policies is **nonconvex** and even might be **not connected**. [Tang, Zheng, Li, 2023]
- ❑ LQR/LQG costs are **smooth but nonconvex**; the Hinf cost is **non-smooth and nonconvex**



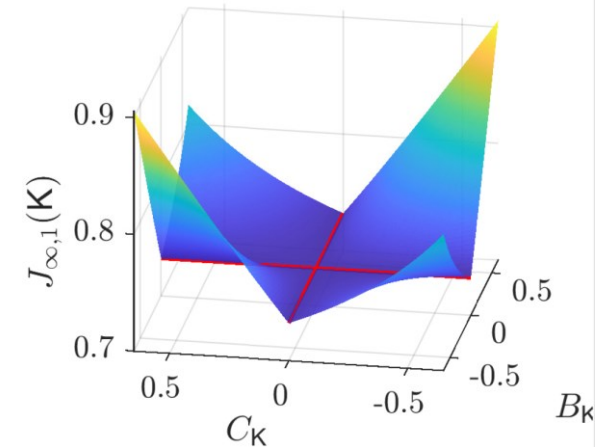
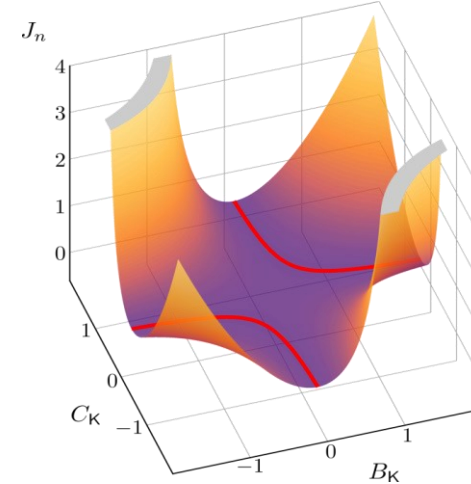
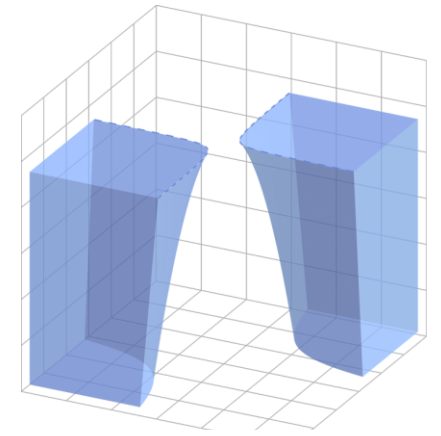
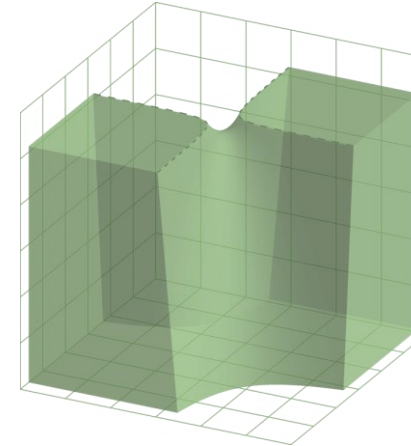
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For all iconic control problems (LQR, LQG, Hinf etc.), any (non-degenerate) **Clarke stationary points are globally optimal!**

Rich Geometry in Policy Optimization

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Non-convex Optimization problem

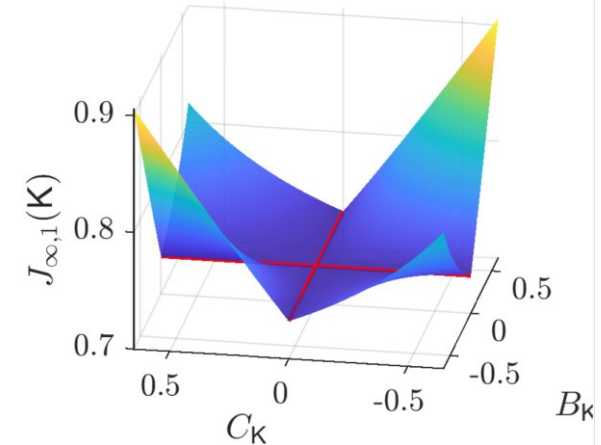
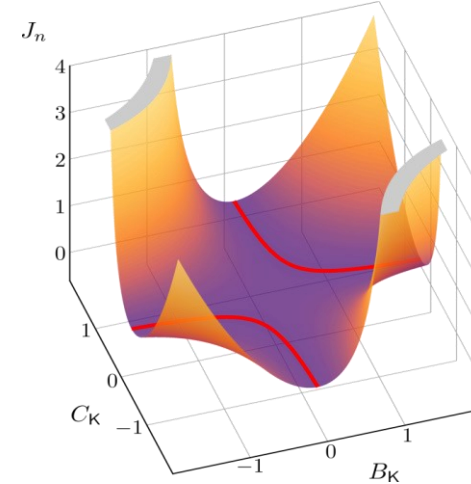
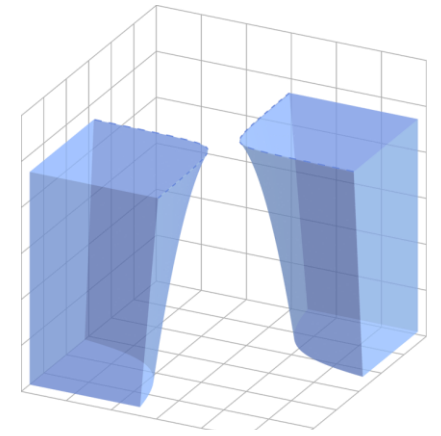
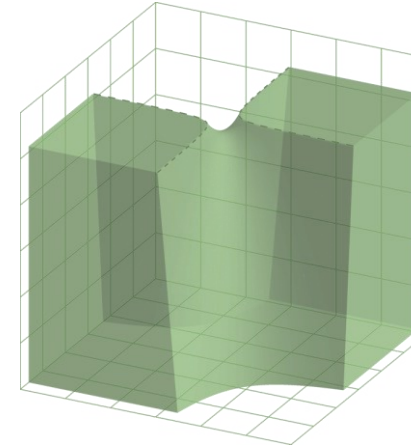
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Local Stationarity



Structural Information

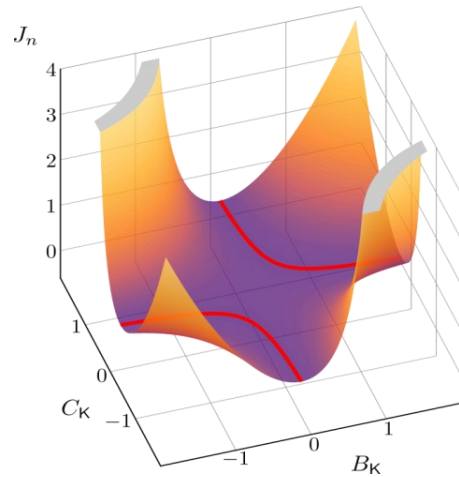
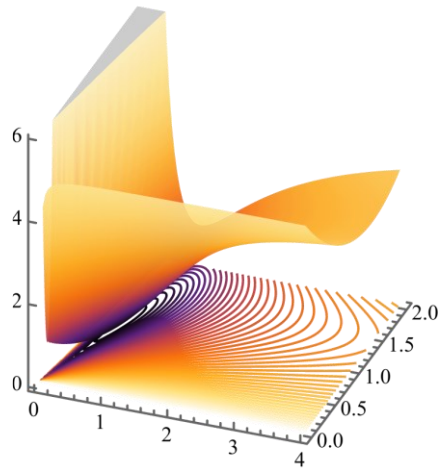
Global Optimality Certificate



For all iconic control problems (LQR, LQG, Hinf etc.), any (non-degenerate) **Clarke stationary points are globally optimal!**

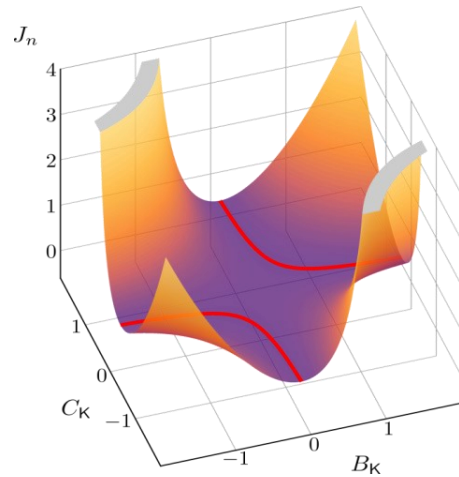
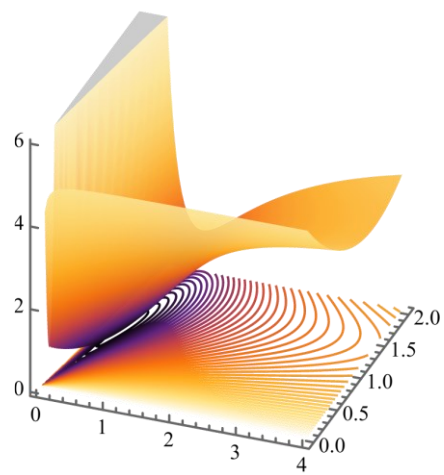
Our Technique: Extended Convex Lifting

Nonconvex Policy Optimization (Modern Perspective)

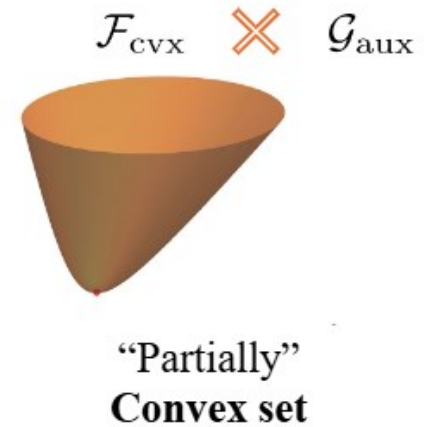
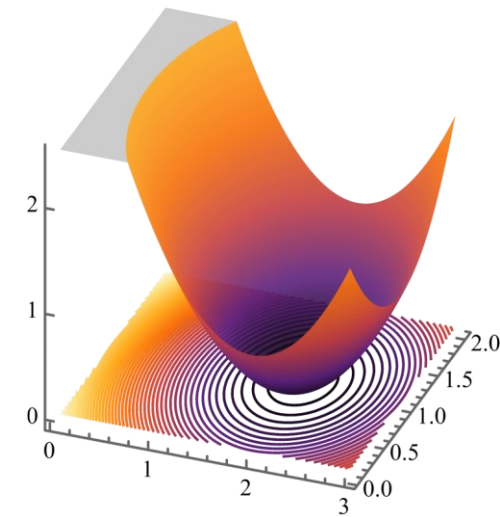


Our Technique: Extended Convex Lifting

Nonconvex Policy Optimization (Modern Perspective)



Convex LMIs (Classical tool)

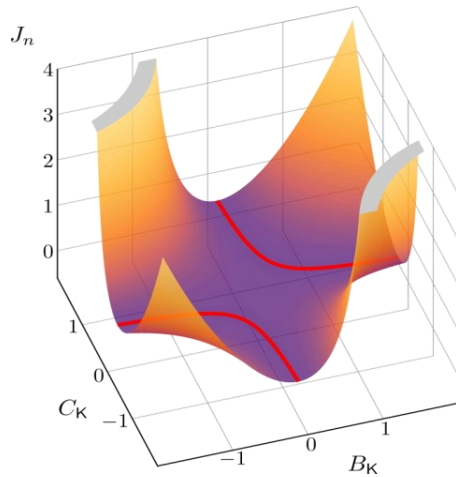
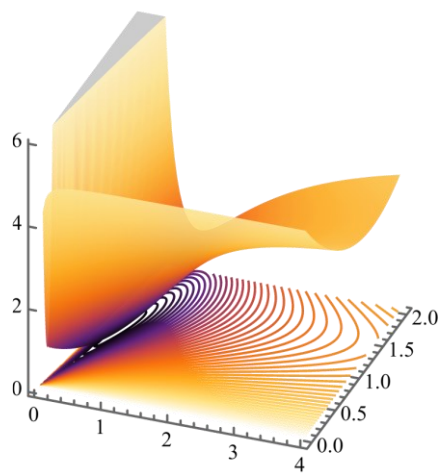


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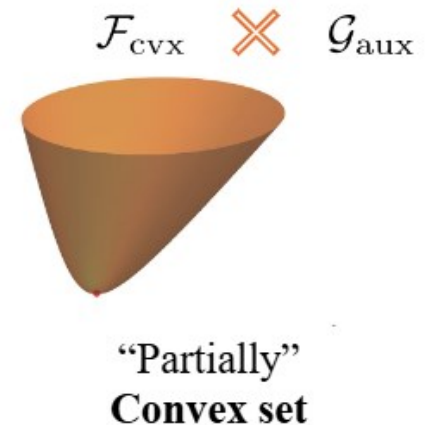
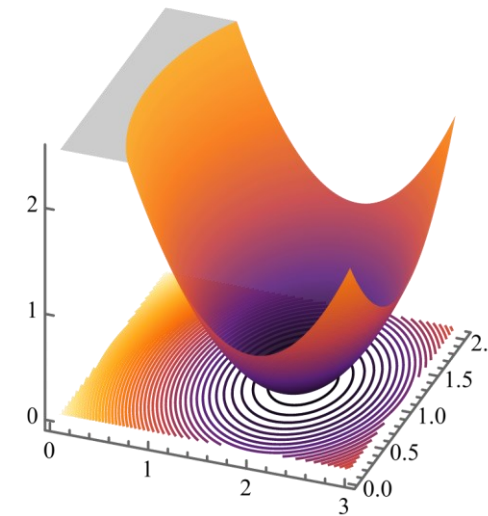
Nonconvex Policy Optimization
(Modern Perspective)

A framework of
Extended Convex Lifting (ECL)

Convex LMIs
(Classical tool)

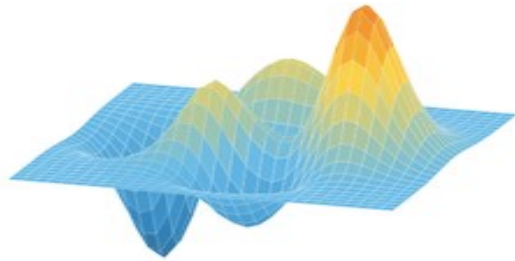


“Invertible” Map



- ❖ Reconciles the gap between **nonconvex policy optimization** and **convex reformulations**.

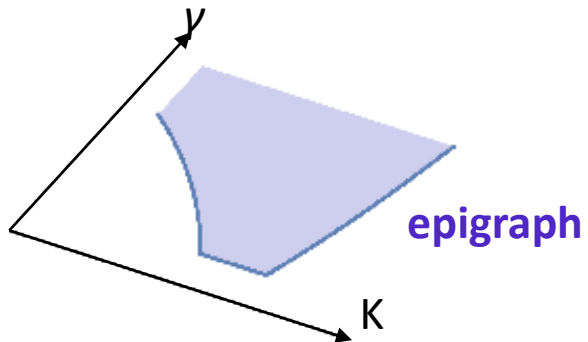
Lifting for Convexity



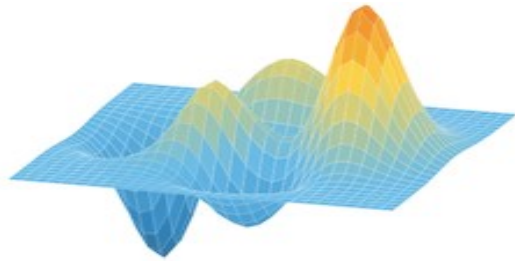
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*Non-convex
Optimization
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- ❑ For many control problems, a **direct convexification is not possible!**
- ❑ **A lifting procedure** corresponding to **Lyapunov variables** is necessary.



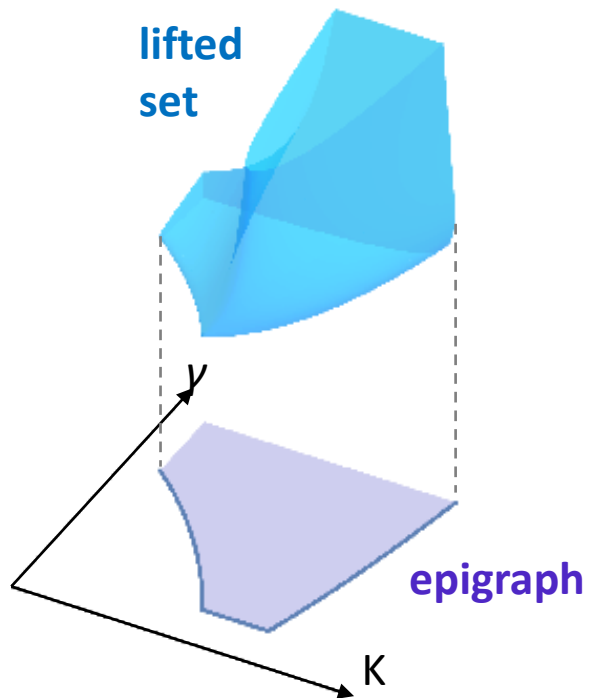
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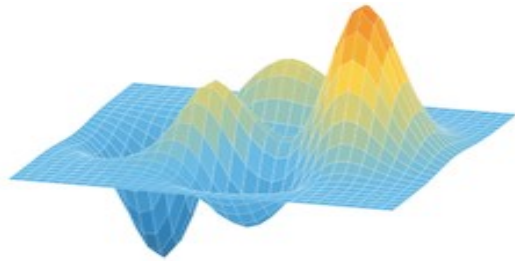
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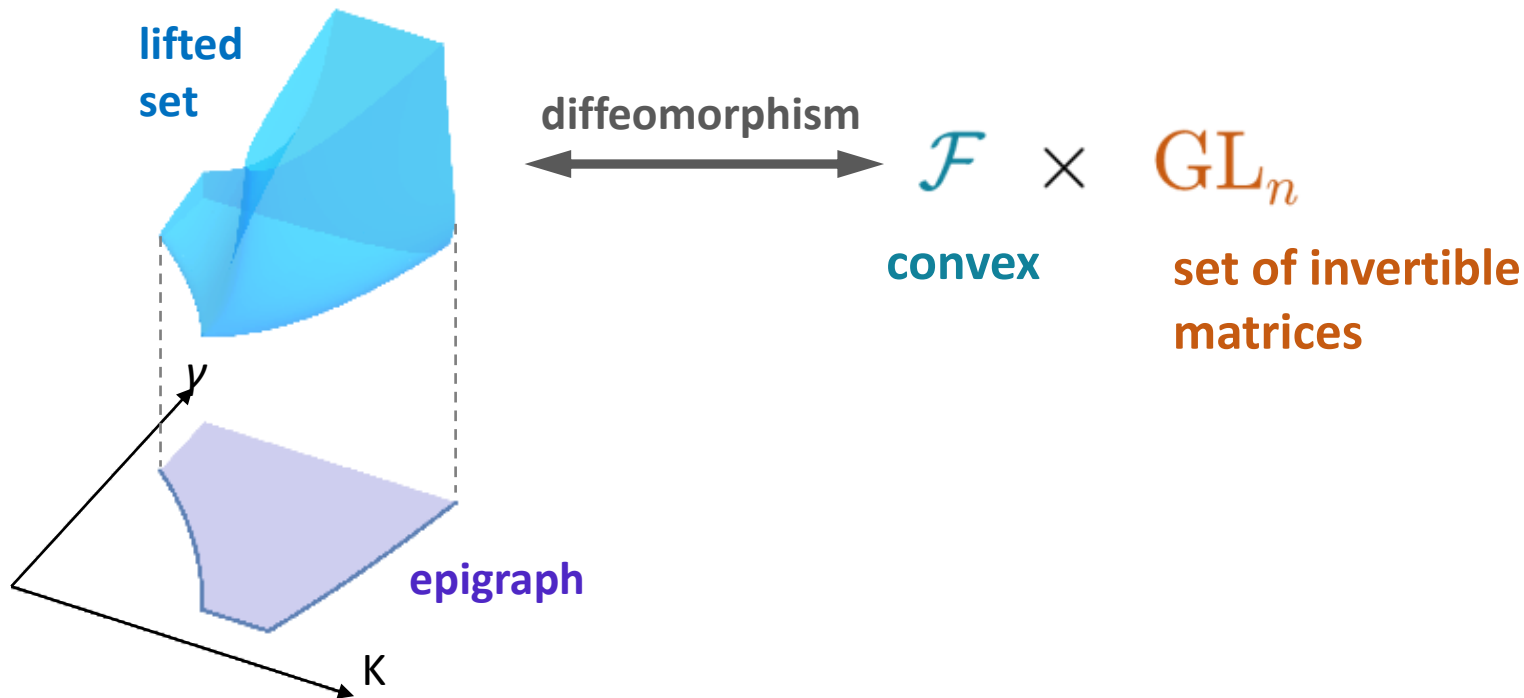
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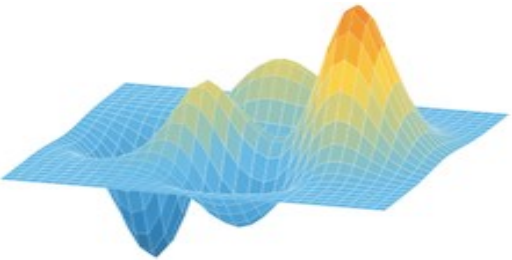
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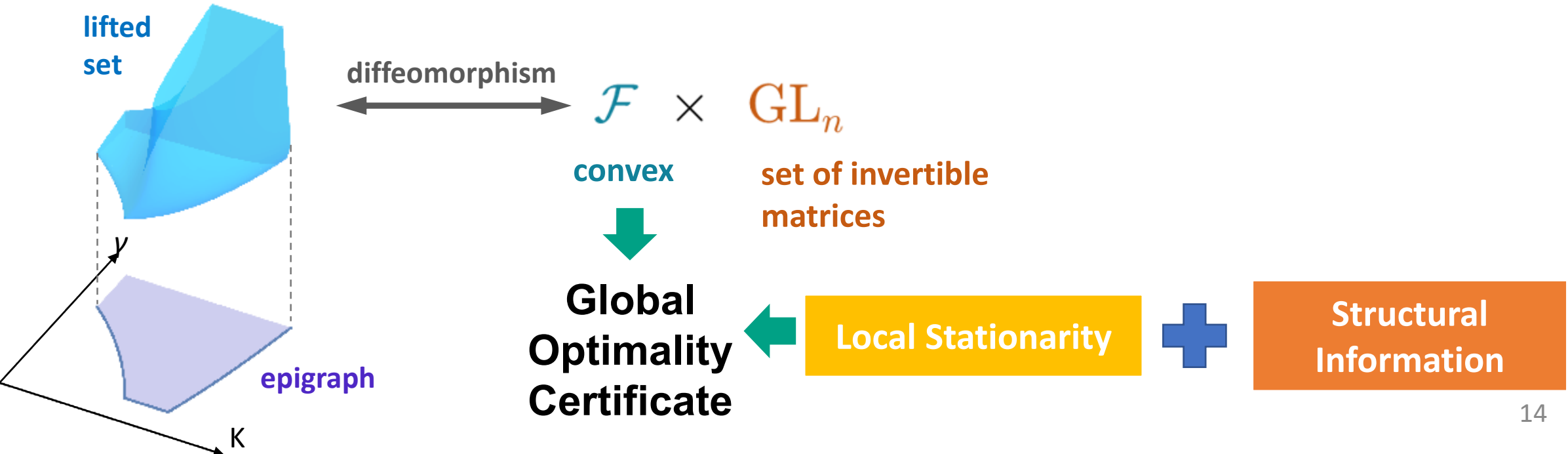
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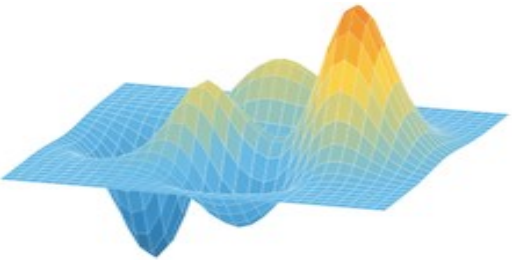
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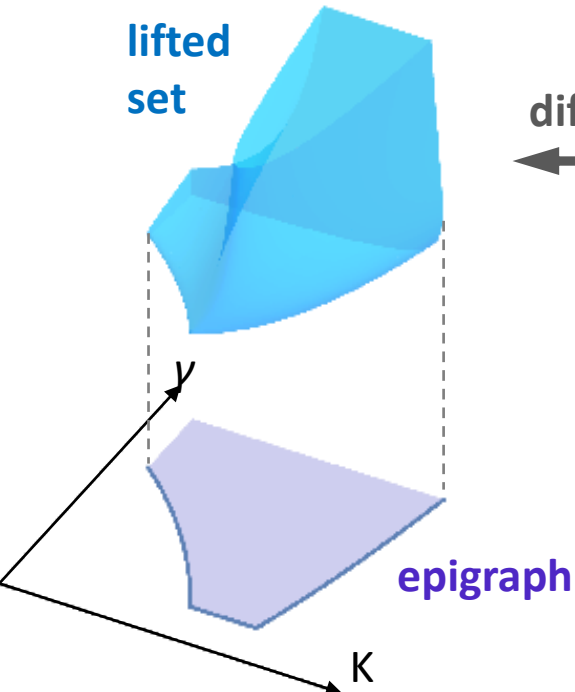
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diffeomorphism

$$\mathcal{F} \times GL_n$$

convex

set of invertible
matrices

**See our poster
for more details!**

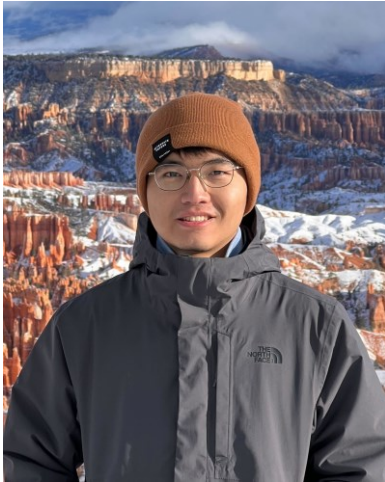
**Global
Optimality
Certificate**

Local Stationarity

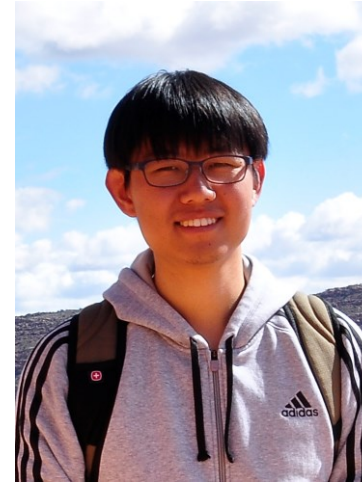


**Structural
Information**

Acknowledgements



Chih-Fan (Rich) Pai
University of California San Diego



Yujie Tang
Peking University



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CMMI-2320697,
CAREER-2340713

- Zheng, Yang, Chih-Fan Pai, and Yujie Tang. "**Benign Nonconvex Landscapes in Optimal and Robust Control, Part I: Global Optimality.**" arXiv preprint arXiv:2312.15332 (2023): <https://arxiv.org/abs/2312.15332>.
- Zheng, Yang, Chih-Fan Pai, and Yujie Tang. "**Benign Nonconvex Landscapes in Optimal and Robust Control, Part II: Extended Convex Lifting.**" arXiv preprint arXiv:2406.04001 (2024): <https://arxiv.org/abs/2406.04001>

